

Communicative spring-return actuator with emergency control function for adjusting dampers in technical building installations

- Air damper size up to approx. 2 m<sup>2</sup>
- Nominal torque 10 Nm
- Nominal voltage AC/DC 24 V
- Control communicative, modulating DC (0)2...10 V Variable
- Position feedback DC 2...10 V Variable
- · Conversion of sensor signals
- · Communication via Belimo MP-Bus





Technical data				
Electrical data	Nominal voltage	AC/DC 24 V		
	Nominal voltage frequency	50/60 Hz		
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V		
	Power consumption in operation	7 W		
	Power consumption in rest position	3.5 W		
	Power consumption for wire sizing	9.5 VA		
	Connection supply / control	Cable 1 m, 4 x 0.75 mm <sup>2</sup>		
	Parallel operation	Yes (note the performance data)		
Functional data	Torque motor	Min. 10 Nm		
	Torque spring return	Min. 10 Nm		
	Positioning signal Y	DC 010 V		
	Positioning signal Y note	Input impedance 100 kΩ		
	Control signal Y variable	Open-close		
	•	3-point (AC only)		
		Modulating (DC 032 V)		
	Operating range Y	DC 210 V		
	Operating range Y variable	Start point DC 0.530 V		
		End point DC 2.532 V		
	Position feedback U	DC 210 V		
	Position feedback U note	Max. 0.5 mA		
	Position feedback U variable	Start point DC 0.58 V End point DC 2.510 V		
	Position accuracy	±5%		
	Direction of motion motor	Selectable with switch L / R		
	Direction of motion variable	Electronically reversible		
	Direction of motion emergency control function	Selectable by mounting L / R		
	Manual override	By means of hand crank and locking switch		
	Angle of rotation	Max. 95°		
	Angle of rotation note	adjustable starting at 33% in 2.5% steps (with mechanical end stop)		
	Running time motor	150 s / 90°		
	Motor running time variable	40150 s		
	Running time emergency control position	<20 s / 90°		
	Running time emergency setting position note	<20 s @ -2050°C / <60 s @ -30°C		
	Adaption setting range	manual		
	Adaption setting range variable	No action		
		Adaption when switched on		
		Adaption after pushing the gear disengagement button		
	Override control	MAX (maximum position) = 100%		
		MIN (minimum position) = 0%		
		ZS (intermediate position, AC only) = 50%		
	Override control variable	MAX = (MIN + 32%)100%		
		MIN = 0%(MAX – 32%)		
	Cound namer lovel mater	ZS = MINMAX		
	Sound power level motor	40 dB(A)		
	Spindle driver	Universal spindle clamp 1025.4 mm		

Mechanically, pluggable

Position indication

# Spring-return actuator, communicative, modulating, AC/DC 24 V, 10 Nm, Communication via Belimo MP-Bus



#### **Technical data**

#### **Functional data**

#### Safety

#### Min. 60,000 emergency positions Service life Protection class IEC/EN III Safety extra-low voltage **UL Class 2 Supply** Protection class UL IP54 Degree of protection IEC/EN NEMA 2, UL Enclosure Type 2 Degree of protection NEMA/UL **EMC** CE according to 2014/30/EU Certification IEC/EN IEC/EN 60730-1 and IEC/EN 60730-2-14 Certification UL cULus according to UL 60730-1A, UL 60730-2-14 and CAN/CSA E60730-1:02 Mode of operation Type 1.AA 0.8 kV Rated impulse voltage supply / control Control pollution degree 3 Ambient temperature -30...50°C Non-operating temperature -40...80°C Ambient humidity 95% r.h., non-condensing Maintenance Maintenance-free Weight 2.2 kg

## Safety notes



Weight

- The device must not be used outside the specified field of application, especially not in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea)water, snow, ice, insolation
  or aggressive gases interfere directly with the actuator and that is ensured that the
  ambient conditions remain at any time within the thresholds according to the data
  sheet.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- The device contains electrical and electronic components and must not be disposed
  of as household refuse. All locally valid regulations and requirements must be
  observed.
- · Cables must not be removed from the device.

## **Product features**

#### Mode of operation

Conventional operation:

The actuator is connected with a standard modulating signal of DC 0...10V and drives to the position defined by the positioning signal. Measuring voltage U serves for the electrical display of the damper position 0...100% and as slave control signal for other actuators.

Operation on the MP-Bus:

The actuator receives its digital positioning signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.

Converter for sensors

Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.

Parameterisable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.

Simple direct mounting

Simple direct mounting on the damper spindle with an universal spindle clamp, supplied with an anti-rotation device to prevent the actuator from rotating.

Manual override

By using the hand crank the damper can be actuated manually and engaged with the locking switch at any position. Unlocking is carried out manually or automatically by applying the operating voltage.

High functional reliability

The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.

Adjustable angle of rotation

Adjustable angle of rotation with mechanical end stops.

# Spring-return actuator, communicative, modulating, AC/DC 24 V, 10 Nm, Communication via Belimo MP-Bus



## **Product features**

## Home position

The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%)

The actuator then moves into the position defined by the positioning signal.

## Adaption and synchronisation

An adaption can be triggered manually by pressing the "Adaption" button or with the PC-Tool. Both mechanical end stops are detected during the adaption (entire setting range). Automatic synchronisation after actuating the hand crank is programmed. The synchronisation is in the home position (0%).

The actuator then moves into the position defined by the positioning signal. A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

## **Accessories**

	Description	Туре
Gateways	Gateway MP to Modbus RTU, AC/DC 24 V	UK24MOD
	Gateway MP for BACnet MS/TP, AC/DC 24 V	UK24BAC
	Gateway MP to LonWorks, AC/DC 24 V, LonMark certified	UK24LON
	Gateway MP to KNX, AC/DC 24 V, EIBA certified	UK24EIB
	Description	Туре
Electrical accessories	Auxiliary switch, 2 x SPDT	S2A-F
	Feedback potentiometer, 200 Ohm, incl. installation accessories	P200A-F
	Feedback potentiometer 1 kOhm, incl. installation accessories	P1000A-F
	Signal converter voltage/current, supply AC/DC 24V	Z-UIC
	Digital position indicator for front-panel mounting, 099%, front mass $72 \times 72 \text{ mm}$	ZAD24
	Range controller for wall mounting, adjustable electron. Min./max. angle of rotation limitation	SBG24
	Positioner for wall mounting, range 0100%	SGA24
	Positioner in a conduit box, range 0100%	SGE24
	Positioner for front-panel mounting, range 0100%	SGF24
	Positioner for wall mounting, range 0100%	CRP24-B1
	Connecting cable 5 m, A+B: RJ12 6/6, To ZTH/ZIP-USB-MP	ZK1-GEN
	Connection cable 5 m, A: RJ11 6/4, B: Free wire end, To ZTH/ZIP-USB-MP	ZK2-GEN
	MP-Bus power supply for MP actuators, AC 230/24V for local power supply	ZN230-24MP
	Connecting board MP bus suitable for wiring boxes EXT-WR-FPMP	ZFP2-MP
	Description	Туре
echanical accessories	Shaft extension 250 mm, for damper spindles Ø 825 mm	AV8-25
	End stop indicator for NFA / SFA	IND-AFB
	Spindle clamp set for NFA/SFA (1", 3/4", 1/2")	K7-2
	Spindle clamp set for NFA/SFA (1", 3/4", 1/2") Straight ball joint with M8, suitable for damper crank arms KH8	K7-2 KG10A
	Straight ball joint with M8, suitable for damper crank arms KH8	KG10A
	Straight ball joint with M8, suitable for damper crank arms KH8 Angled ball joint with M8, suitable for damper crank arms KH8	KG10A KG8
	Straight ball joint with M8, suitable for damper crank arms KH8 Angled ball joint with M8, suitable for damper crank arms KH8 Damper crank arm, for damper spindles	KG10A KG8 KH8
	Straight ball joint with M8, suitable for damper crank arms KH8 Angled ball joint with M8, suitable for damper crank arms KH8 Damper crank arm, for damper spindles Damper crank arm for NFA / SFA, for 3/4" spindles	KG10A KG8 KH8 KH-AFB
	Straight ball joint with M8, suitable for damper crank arms KH8 Angled ball joint with M8, suitable for damper crank arms KH8 Damper crank arm, for damper spindles Damper crank arm for NFA / SFA, for 3/4" spindles Form fit insert 10x10 mm, for spring return actuators NG	KG10A KG8 KH8 KH-AFB ZF10-NSA-F
	Straight ball joint with M8, suitable for damper crank arms KH8 Angled ball joint with M8, suitable for damper crank arms KH8 Damper crank arm, for damper spindles Damper crank arm for NFA / SFA, for 3/4" spindles Form fit insert 10x10 mm, for spring return actuators NG Form fit insert 12x12 mm, for spring return actuators NG Form fit insert 16x16 mm, for spring return actuators NG	KG10A KG8 KH8 KH-AFB ZF10-NSA-F ZF12-NSA-F ZF16-NSA-F
	Straight ball joint with M8, suitable for damper crank arms KH8 Angled ball joint with M8, suitable for damper crank arms KH8 Damper crank arm, for damper spindles Damper crank arm for NFA / SFA, for 3/4" spindles Form fit insert 10x10 mm, for spring return actuators NG Form fit insert 12x12 mm, for spring return actuators NG	KG10A KG8 KH8 KH-AFB ZF10-NSA-F ZF12-NSA-F
	Straight ball joint with M8, suitable for damper crank arms KH8 Angled ball joint with M8, suitable for damper crank arms KH8 Damper crank arm, for damper spindles Damper crank arm for NFA / SFA, for 3/4" spindles Form fit insert 10x10 mm, for spring return actuators NG Form fit insert 12x12 mm, for spring return actuators NG Form fit insert 16x16 mm, for spring return actuators NG Damper crank arm, for spring return actuators NG	KG10A KG8 KH8 KH-AFB ZF10-NSA-F ZF12-NSA-F ZF16-NSA-F ZG-AFB
Service Tools	Straight ball joint with M8, suitable for damper crank arms KH8 Angled ball joint with M8, suitable for damper crank arms KH8 Damper crank arm, for damper spindles Damper crank arm for NFA / SFA, for 3/4" spindles Form fit insert 10x10 mm, for spring return actuators NG Form fit insert 12x12 mm, for spring return actuators NG Form fit insert 16x16 mm, for spring return actuators NG Damper crank arm, for spring return actuators NG Base plate extensions for NFA/SFA	KG10A KG8 KH8 KH-AFB ZF10-NSA-F ZF12-NSA-F ZF16-NSA-F ZG-AFB Z-SF
Service Tools	Straight ball joint with M8, suitable for damper crank arms KH8 Angled ball joint with M8, suitable for damper crank arms KH8 Damper crank arm, for damper spindles Damper crank arm for NFA / SFA, for 3/4" spindles Form fit insert 10x10 mm, for spring return actuators NG Form fit insert 12x12 mm, for spring return actuators NG Form fit insert 16x16 mm, for spring return actuators NG Damper crank arm, for spring return actuators NG Base plate extensions for NFA/SFA  Description  Service Tool, for MF/MP/Modbus/LonWorks actuators and VAV-	KG10A KG8 KH8 KH-AFB ZF10-NSA-F ZF12-NSA-F ZF16-NSA-F ZG-AFB Z-SF



## **Electrical installation**

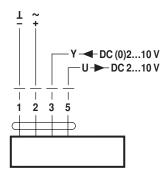


#### **Notes**

- · Connection via safety isolating transformer.
- Parallel connection of other actuators possible. Observe the performance data.

#### Wiring diagrams

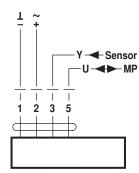
AC/DC 24 V, modulating



#### Cable colours:

- 1 = black
- 2 = red
- 3 = white
- 5 = orange

#### Operation on the MP-Bus



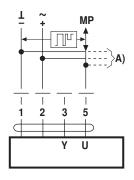
#### Cable colours:

- 1 = black
- 2 = red
- 3 = white
- 5 = orange

## **Functions**

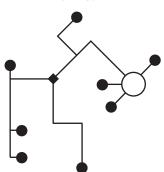
#### Functions when operated on MP-Bus

Connection on the MP-Bus



A) more actuators and sensors (max.8)

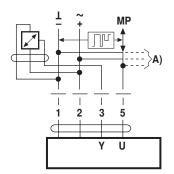
#### Network topology



There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable

- no shielding or twisting necessary
- · no terminating resistors required

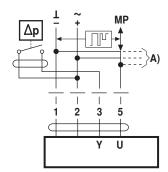
Connection of active sensors



A) more actuators and sensors (max.8)

- Supply AC/DC 24 V
- Output signal DC 0...10 V (max. DC 0...32 V)
- Resolution 30 mV

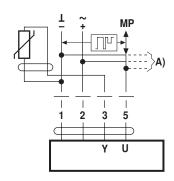
#### Connection of external switching contact



A) more actuators and sensors (max.8)

- Switching current 16 mA @ 24 V
- Start point of the operating range must be parameterised on the MP actuator as ≥ 0.5 V

## Connection of passive sensors



Ni1000	–28+98°C	8501600 Ω <sup>2)</sup>
PT1000	−35+155°C	8501600 Ω <sup>2)</sup>
NTC	-10+160°C 1)	200 Ω60 kΩ 2)

A) more actuators and sensors (max.8)

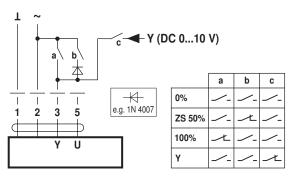
- Depending on the type
- 2) Resolution 1 Ohm



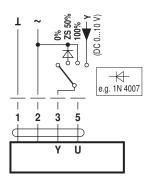
## **Functions**

#### Functions with basic values (conventional mode)

Override control with AC 24 V with relay contacts

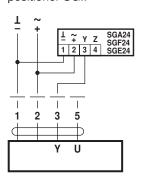


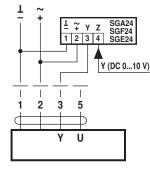
Override control with AC 24 V with rotary switch

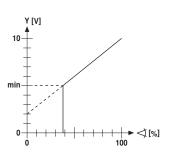


Remote control 0...100% with positioner SG..

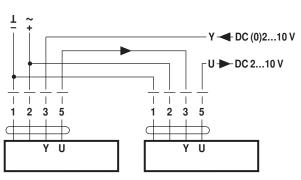
 $\label{eq:minimum limit with positioner SG.} Minimum limit with positioner SG..$ 



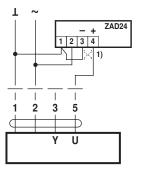




Follow-up control (position-dependent)



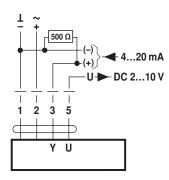
Position indication



Control with 4...20 mA via external resistor

Functional check

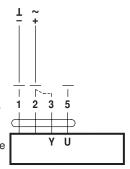
(1) Adapting the direction of rotation



#### Caution:

The operating range must be set to DC 2...10 V.

The 500  $\Omega$  resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V



#### Procedure

- 1. Connect 24V to connections 1 and 2
- 2. Disconnect connection 3:
- with direction of rotation 0:
- Actuator rotates to the left
- with direction of rotation 1:Actuator rotates to the right
- 3. Short-circuit connections 2 and 3:
- Actuator runs in opposite direction

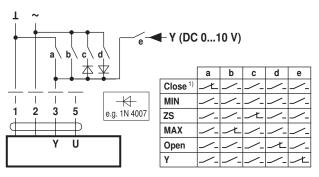


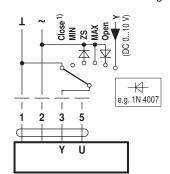
## **Functions**

## Functions for actuators with specific parameters (Parametrisation with PC-Tool necessary)

Override control and limiting with AC 24 V with relay contacts

Override control and limiting with AC 24 V with rotary switch

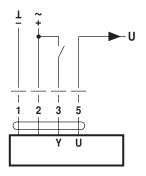


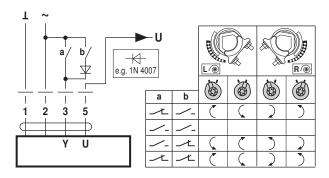


1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

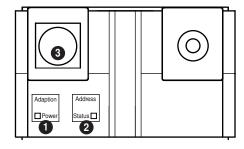
Control open-close

Control 3-point





## Operating controls and indicators



## Membrane key and LED display green

Off: No power supply or malfunction

On: In operation

Press button: Triggers angle of rotation adaptation, followed by standard mode

#### 2 Membrane key and LED display gelb

Off: Standard mode

Flickering: MP communication active

On: Adaptation and synchronising process active Flashing: Request for addressing from MP master

Press button: Confirmation of the addressing

## 3 Service plug

For connecting parameterisation and service tools

#### Operating elements

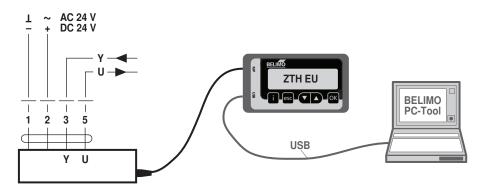
The manual override, locking switch and direction of rotation switch elements are available on both sides



## Service

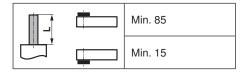
#### **Service Tools connection**

The actuator can be parameterised by ZTH EU via the service socket. For an extended parameterisation the PC tool can be connected.

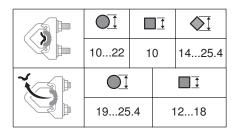


## **Dimensions [mm]**

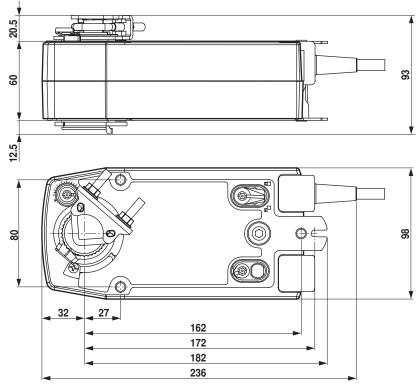
## Spindle length



#### Clamping range



## **Dimensional drawings**



## **Further documentation**

- Overview MP Cooperation Partners
- Tool connections